

# Higher order complexity

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# Type two Theory of Effectivity

## Computability

- Represented spaces, admissibility (Weihrauch)
- Extended admissibility, on QCB-spaces (Schröder)

## Complexity

- Kawamura and Cook :  $Reg \subseteq \Sigma^* \rightarrow \Sigma^*$
- Polynomial time complexity based on  $BFF_2$
- allows to define notions of complexity over non  $\sigma$ -compact spaces like  $\mathcal{C}([0, 1], \mathbb{R})$

# "Feasible" admissibility

## Definition (Polynomial reducibility)

$\delta \leq_P \delta'$  if  $\delta = \delta' \circ f$  with  $f$  polynomial time computable

## Theorem (Kawamura & Cook)

$\delta_{\square}$  is the "largest" representation of  $\mathcal{C}([0, 1], \mathbb{R})$  making  
 $Eval : \mathcal{C}([0, 1], \mathbb{R}) \rightarrow [0, 1] \rightarrow \mathbb{R}$  polynomial time computable.

→ For which spaces can we do the same?

# First order representations are not sufficient

## Theorem

*Let  $X$  be a Polish space that is not  $\sigma$ -compact. Then there is no representation of  $\mathcal{C}(X, \mathbb{R})$  making the time complexity of  $\text{Eval}_{X, \mathbb{R}} : \mathcal{C}(X, \mathbb{R}) \times X \rightarrow \mathbb{R}$  well-defined.*

*( $X = \mathcal{C}([0, 1], \mathbb{R})$  for example) b*

## Lemma

*There is no surjective partial continuous function  $\phi : (\mathbb{N} \rightarrow \mathbb{N}) \rightarrow \mathcal{C}(\mathbb{N} \rightarrow \mathbb{N}, \mathbb{N})$  bounded by a total continuous function.*

## Corollary

*"Higher order is required to define complexity-friendly representations."*

# Higher order complexity

**Finite types:**  $\tau = \mathbb{N} \mid \tau_1 \times \dots \times \tau_n \rightarrow \mathbb{N}$

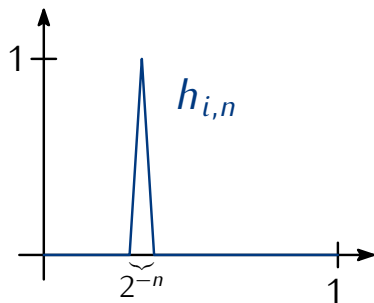
A notion of feasibility at all finite types: BFF.

**Problem:** Some intuitively feasible functionals are not in BFF.

**Example**

$$\Gamma : (\mathcal{C}([0, 1], \mathbb{R}) \rightarrow \mathbb{R}) \times \mathbb{N} \rightarrow \mathbb{R}$$

$$\Gamma(F, n) = \prod_{0 \leq i \leq 2^n} (1 + |F(h_{i,n})|)$$



# Higher order strategies

$$\begin{array}{c}
 \text{Player} \\
 \overbrace{((\overset{x}{\mathbb{N}} \rightarrow \overset{g}{\mathbb{N}}) \rightarrow \overset{f}{\mathbb{N}}) \rightarrow \overset{F}{\mathbb{N}}} \\
 \underbrace{\hspace{10em}} \\
 \text{Opponent}
 \end{array}$$

**Moves:**  $?^f$  or  $!^f(v)$  + justifications.

## Definition

A strategy is a function which given a list of previous moves, outputs a valid move.

# Examples

- $x = 3$

$$\frac{}{\text{?}^x} !^x(3)$$

- $f(x) = 2x + 1$

$$\frac{}{\text{?}^f} \text{?}^x \frac{}{\text{?}^x(n)} !^x(2n + 1)$$

- $F(g) = g(\lambda x.x) + 1$

$$\frac{}{\text{?}^F} \text{?}^g \frac{}{\text{?}^g(n)} !^g(n+1) \quad \frac{}{\text{?}^h} \text{?}^x \frac{}{\text{?}^x(n)} !^h(n) \quad \frac{}{\text{?}^g(m)} !^g(m+1) \quad \frac{}{\text{?}^h} \text{?}^x \dots$$

# Examples

- $x = 3$

$$\frac{}{\textcolor{red}{?}^x} \textcolor{blue}{!}^x(3)$$

- $f(x) = 2x + 1$

$$\frac{\textcolor{red}{?}^f}{\textcolor{blue}{?}^x} \frac{\textcolor{red}{!}^x(n)}{\textcolor{blue}{?}^x} \frac{\textcolor{red}{!}^x(n)}{\textcolor{blue}{?}^x} \frac{\textcolor{red}{!}^x(n)}{\textcolor{blue}{?}^x} \textcolor{blue}{!}^f(2n + 1)$$

- $F(g) = g(\lambda x.x) + 1$

$$\begin{array}{c} \textcolor{red}{?}^F \textcolor{blue}{?}^g \frac{\textcolor{red}{!}^g(n)}{\textcolor{blue}{!}^F(n+1)} \\ \quad \swarrow \textcolor{red}{?}^h \\ \quad \textcolor{blue}{?}^x \frac{\textcolor{red}{!}^x(n)}{\textcolor{blue}{!}^h(n)} \frac{\textcolor{red}{!}^g(m)}{\textcolor{blue}{!}^F(m+1)} \\ \quad \quad \swarrow \textcolor{red}{?}^h \\ \quad \quad \textcolor{blue}{?}^x \dots \end{array}$$



# Examples

- $x = 3$

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- $f(x) = 2x + 1$

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- $F(g) = g(\lambda x.x) + 1$

$$\frac{}{\text{?}^F} \text{?}^g \frac{}{\text{?}^h} \frac{}{\text{?}^x} \frac{}{\text{?}^h} \frac{}{\text{?}^x} \dots$$

$H$

# Size of a strategy

## Definition

$$S_s(b_1, \dots, b_n) = \max_{(s_1, \dots, s_n) \in K_{b_1} \times \dots \times K_{b_n}} |H(s, s_1, \dots, s_n)|$$

$$K_b = \{s' \mid S_{s'} \preceq b\}$$

## Example

- $n \in \mathbb{N}$  has a strategy of size  $\mathcal{O}(\log_2 n)$ .
- $f : \mathbb{N} \rightarrow \mathbb{N}$  has a strategy of size  $|f|(n) = \max_{|x| \leq n} |f(x)|$ .
- The size of a strategy for  $F : (\mathbb{N} \rightarrow \mathbb{N}) \rightarrow \mathbb{N}$  is at least its modulus of continuity.

# Higher order Turing machines

## Definition (HOTM)

A HOTM is a kind of oracle Turing machine which plays a game versus its oracles.

## Property

*A strategy is computable  $\iff$  it is represented by a HOTM.*

**Run-time** of a HOTM: same as for an OTM.

# Polynomial time complexity

## Definition (Higher type polynomials )

$HTP$  = simply-typed  $\lambda$ -calculus with  $+, * : \mathbb{N} \times \mathbb{N} \rightarrow \mathbb{N}$ .

## Property

*HTP of type 1 and 2 are respectively the usual polynomials and the second-order polynomials.*

## Example

The complexity of  $\Gamma$  is about  $\mathcal{F}, n \mapsto \mathcal{F}(\lambda x.c) \times \mathcal{F}(\lambda y.P(y, n))$

# Higher order representations

## Definition (Kleene-Kreisel Spaces)

$$KKS = [\mathbb{N}, \subseteq, \rightarrow, \times]$$

## Definition (Representation)

A representation  $\delta$  of a space  $X$  with a *KKS*  $A$  is a surjective function from  $A$  to  $X$ .

## Definition (Polynomial reduction)

$\delta_1 \leq_P \delta_2$  if  $\delta_1 = \delta_2 \circ F$  for some polynomial time computable  $F : A_1 \rightarrow A_2$ .

# Standard representation of $\mathcal{C}(X, Y)$

## Definition

$\delta_{\mathcal{C}(X, Y)}(F) = f$  whenever  $f \circ \delta_X = \delta_Y \circ F$

## Property

*Eval :  $\mathcal{C}(X, Y) \times X \rightarrow Y$  is polynomial-time computable w.r.t.  $(\delta_{\mathcal{C}(X, Y)}, \delta_X, \delta_Y)$*

## Theorem

*It is the largest representation making Eval polynomial.*

# Conclusion

- we have a definition of higher order complexity
- new representation spaces
- we need to understand the difference with BFF
- study the notion of admissibility of such representations (c.f. Schröder).